DEPARTMENT OF INFORMATION TECHNOLOGY

VR SIDDHARTHA ENGINEERING COLLEGE

STUDENT INNOVATIVE PROJECTS

<u>2019-20</u>

S.NO	ROLL NO	NAME OF	YEAR	IDEA TITLE	DESCRIPTION OF THE INNOVATION	
		THE	-SEC			
1	100111 4 1200	SIUDENI D D1 G	TT A	T (A 1		
1	188W1A1209	B Bhanu Sri	II-A	Lost And	This device enables us to find our small things like wallet, spectacles, keys etc. every	
		Vaishnavi		Found	day. We humans forget our daily belongings every day. So the device we do will help	
	188W1A1231	M.K. Snigdha	II-A		you to find it easily. The device can be attached to any of our daily belongings like phone,	
					spectacles, keys etc. that will be connected through our mobile or a physical button. The	
				device alarms when we click the button physically or through our mobile connected to		
				the device. It helps to find the lost things in close proximity. So it helps to find our things		
					easily every day. The device can be connected through mobile hotspot or WI-FI. To	
2	170111 4 10 4 (<u>.</u>	develop a device which helps to find the lost stuff in our nome attached to it.	
2	1/8WIA1246	R.V.Neel	III-A	Sign	Deaf and dumb people use sign language for communication. This is not understood by	
		Kamal		Language	Language general people; hence their interaction with others is limited. Hence we developed	
	178W1A1206	Ch.V.N.	III-A	Interpreter	application using Deep Learning to solve this issue	
		Koushik				
	178W1A1228	K.Dinesh Teja	III-A			
3	178W1A1261	A.Srikanth	III-B	Wireless	The main aim of the project is to charge the electric vehicles when they were	
	178W1A1286	I N N Krishna	III-B	Charging Car	placed in a parking area or a specified area. If an electric vehicle needs to be charged	
		Sai			whenever they required, but that may not be possible all the time. So,	whenever they required, but that may not be possible all the time. So, we implementing
				this project to charge that vehicles whenever they required. This were placed in		
					restaurant, malls, hospitals parking places to charge by the time they complete their	
					work.	
4	178W1A1218	G.Gowri Nagh	III-A	Road Safety	Roads became a dangerous place as many accidents are taking place every day. We	
	178W1A1241	P.Sri Varun	III-A	At Night	cannot avoid few accidents. Many of the avoidable accidents occur at night time. This	
	178W1A1205	Ch.Tarun	III-A		project provides solutions for these accidents.	

5	178W1A1212	D.Veda Sree	III-A	Smart Street	This project is about Smart street light, street light will turn on while vehicle is passing
	178W1A1250	S.Harika	III-A	Light System	through it. Here we are using 4 IR sensors that senses the position of the vehicle, each IR
					sensor controls 3 LED's. When vehicle passes by a particular IR sensor it senses the
					position of vehicle and gives its signal to the arduino board and it will turn on the LED's.
6	178W1A1257	V.Triveni	III-A	Traffic	Required components are mounted on PCB as per the component layout diagram 1 and
	178W1A1245	R.Gowri	III-A	Density	soldered. Traffic lights model layout for a four junction road is drawn on the wooden
		Priyanka		Control and	board. 4 green and 4 red LEDs are mounted at the center on four sides. 8 IR LED's and 8
	178W1A1207	Ch.Swapna	III-A	Ambulance	photo diodes are mounted on four sides of the road at different distances. LCD and
				Detection	transformer are also mounted on the board. Wire connections are done from the PCB to
					LCD, transformer, IR LEDs, photodiodes, Red and Green LED's. Program code is loaded
-	1503311 + 10 (4	D D'	TH D	.	into the Microcontroller (89c52).
	178W1A1264	Barma Divya	III-B	Farm's	Farmers depend on rain to nourish crops, but too much rain can actually harm crop
		Sri		Umbrella	production. Rain floods fields, washing away seeds and precious topsoil. Also, the rain is
	178W1A1298	Lekhya Sahithi	III-B		causing ditches, which is leaving gaping holes in the middle of <i>fields</i> . Thus rainfall is
		Panchumarth			naving a lot of negative effect on agriculture. In order to overcome this we are providing
					a model where an automatic roof arises on the field to protect it from bad effects of
0	170W1 A 1007	T Toos and as a		Distance	
				1 110101000	I his project is designed to develop distance measurement lising ultraconic waves and
0	1/8W1A128/	J.Jyostna D.Jamaama		Distance	This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduing. Ultra sonic sensors are great tools to measure distance without
0	178W1A1287 178W1A1268	B.Jameema	III-B III-B	Measurement	This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection
0	178W1A1287 178W1A1268	B.Jameema	III-B III-B	Measurement	interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection etc. Basic principle of ultrasonic distance measurement is based on ECHO. This is an
0	178W1A1287 178W1A1268	B.Jameema	III-B III-B	Measurement	This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection etc. Basic principle of ultrasonic distance measurement is based on ECHO. This is an effective way to measure small distances precisely. In this project, we used an ultrasonic
0	178W1A1287 178W1A1268	B.Jameema	III-B III-B	Measurement	This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection etc. Basic principle of ultrasonic distance measurement is based on ECHO. This is an effective way to measure small distances precisely. In this project, we used an ultrasonic sensor to determine the distance of an obstacle from the sensor. When sound waves are
0	178W1A1287 178W1A1268	B.Jameema	III-B III-B	Measurement	This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection etc. Basic principle of ultrasonic distance measurement is based on ECHO. This is an effective way to measure small distances precisely. In this project, we used an ultrasonic sensor to determine the distance of an obstacle from the sensor. When sound waves are transmitted in environment then waves returned back to origin as ECHO after striking on
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9	178W1A1287 178W1A1268 178W1A12B3	B.Jameema S.Sai Keerthana	III-B III-B III-B	Automatic	This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection etc. Basic principle of ultrasonic distance measurement is based on ECHO. This is an effective way to measure small distances precisely. In this project, we used an ultrasonic sensor to determine the distance of an obstacle from the sensor. When sound waves are transmitted in environment then waves returned back to origin as ECHO after striking on the obstacle.
9	178W1A1287 178W1A1268 178W1A12B3 178W1A12B3	S.Sai Keerthana M.Teenu	III-B III-B III-B III-B	Automatic Car Parking	This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection etc. Basic principle of ultrasonic distance measurement is based on ECHO. This is an effective way to measure small distances precisely. In this project, we used an ultrasonic sensor to determine the distance of an obstacle from the sensor. When sound waves are transmitted in environment then waves returned back to origin as ECHO after striking on the obstacle. The IR Sensor placed at the entrance detects the car and displays empty slots which are available to park the car and if the slots are filled, it displays slots are full.
9	178W1A1287 178W1A1268 178W1A12B3 178W1A12B3 178W1A12A4	S.Sai Keerthana M.Teenu Sahasra	III-B III-B III-B III-B	Automatic Car Parking Using	This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection etc. Basic principle of ultrasonic distance measurement is based on ECHO. This is an effective way to measure small distances precisely. In this project, we used an ultrasonic sensor to determine the distance of an obstacle from the sensor. When sound waves are transmitted in environment then waves returned back to origin as ECHO after striking on the obstacle. The IR Sensor placed at the entrance detects the car and displays empty slots which are available to park the car and if the slots are filled, it displays slots are full.
9	178W1A1287 178W1A1268 178W1A12B3 178W1A12B3 178W1A12A4	S.Sai Keerthana M.Teenu Sahasra	III-B III-B III-B III-B	Automatic Car Parking Using Arduino	This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection etc. Basic principle of ultrasonic distance measurement is based on ECHO. This is an effective way to measure small distances precisely. In this project, we used an ultrasonic sensor to determine the distance of an obstacle from the sensor. When sound waves are transmitted in environment then waves returned back to origin as ECHO after striking on the obstacle. The IR Sensor placed at the entrance detects the car and displays empty slots which are available to park the car and if the slots are filled, it displays slots are full.
9	178W1A1287 178W1A1268 178W1A12B3 178W1A12A4 178W1A1284	J.Jyostna B.Jameema S.Sai Keerthana M.Teenu Sahasra G.Sahithi	III-B III-B III-B III-B	Automatic Car Parking Using Arduino Gas Detector	This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection etc. Basic principle of ultrasonic distance measurement is based on ECHO. This is an effective way to measure small distances precisely. In this project, we used an ultrasonic sensor to determine the distance of an obstacle from the sensor. When sound waves are transmitted in environment then waves returned back to origin as ECHO after striking on the obstacle. The IR Sensor placed at the entrance detects the car and displays empty slots which are available to park the car and if the slots are filled, it displays slots are full.
9	178W1A1287 178W1A1268 178W1A12B3 178W1A12B3 178W1A12A4 178W1A1284 178W1A12A6	J.Jyostna B.Jameema S.Sai Keerthana M.Teenu Sahasra G.Sahithi N.Anusha	III-B III-B III-B III-B III-B	Automatic Car Parking Using Arduino Gas Detector	This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection etc. Basic principle of ultrasonic distance measurement is based on ECHO. This is an effective way to measure small distances precisely. In this project, we used an ultrasonic sensor to determine the distance of an obstacle from the sensor. When sound waves are transmitted in environment then waves returned back to origin as ECHO after striking on the obstacle. The IR Sensor placed at the entrance detects the car and displays empty slots which are available to park the car and if the slots are filled, it displays slots are full. While LPG is an essential need of every household, its leakage could lead to a disaster. To alert on LPG leakage and prevent any mis happening there are various products to detect
9	178W1A1287 178W1A1268 178W1A12B3 178W1A12A4 178W1A12A4 178W1A12A4	J.Jyostna B.Jameema S.Sai Keerthana M.Teenu Sahasra G.Sahithi N.Anusha	III-B III-B III-B III-B III-B	Automatic Car Parking Using Arduino Gas Detector	 This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection etc. Basic principle of ultrasonic distance measurement is based on ECHO. This is an effective way to measure small distances precisely. In this project, we used an ultrasonic sensor to determine the distance of an obstacle from the sensor. When sound waves are transmitted in environment then waves returned back to origin as ECHO after striking on the obstacle. The IR Sensor placed at the entrance detects the car and displays empty slots which are available to park the car and if the slots are filled, it displays slots are full. While LPG is an essential need of every household, its leakage could lead to a disaster. To alert on LPG leakage and prevent any mis happening there are various products to detect the leakage. Here we have developed an Arduino based LPG gas detector alarm. If gas
9	178W1A1287 178W1A1268 178W1A12B3 178W1A12A4 178W1A12A4 178W1A12A4	J.Jyostna B.Jameema S.Sai Keerthana M.Teenu Sahasra G.Sahithi N.Anusha	III-B III-B III-B III-B III-B	Automatic Car Parking Using Arduino Gas Detector	This project is designed to develop distance measurement using ultrasonic waves and interfaced with arduino. Ultra sonic sensors are great tools to measure distance without actual contact and used at several place like water level measurement, object detection etc. Basic principle of ultrasonic distance measurement is based on ECHO. This is an effective way to measure small distances precisely. In this project, we used an ultrasonic sensor to determine the distance of an obstacle from the sensor. When sound waves are transmitted in environment then waves returned back to origin as ECHO after striking on the obstacle. The IR Sensor placed at the entrance detects the car and displays empty slots which are available to park the car and if the slots are filled, it displays slots are full. While LPG is an essential need of every household, its leakage could lead to a disaster. To alert on LPG leakage and prevent any mis happening there are various products to detect the leakage. Here we have developed an Arduino based LPG gas detector alarm. If gas leakage occurs, this system detects it and makes an alert by buzzing the buzzer attached

11	178W1A1278	Dollynithisha M	III-B	Smart Dustbin	The system consists of a PIR sensor in order to detect human motion and the lid of the
	178W1A1291	K.Rikhita	III-B		bin is opened automatically using a servo motor without anyone needing to press its
	188W1A1261	A.Sneha	II-B		lever. An Ultrasonic sensor is placed on top of the garbage bin which will detect the total
					level of garbage inside it according to the total size of the bin. When the garbage will
					reach the maximum level, a pin will be sent to the municipalities,(This alert pin is sent to
					the municipal office using GSM module) and the bin gets locked until the employees take
					further actions to empty the bin. Once the dustbin is squashed, people can reuse the
					dustbin. This system will help in cleaning the city in a better way. All the sensors and
					GSM module are connected to Arduino and they are coded in Arduino programming.
12	188W1A1215	Chinnni	II-A	The Serving	The principle is to "SERVE FROM YOUR SEAT". The model is a receiver - transmitter
		Nagasai		Robot	module serving robot that assists in serving. The robot is operated by having a glance of
		Mudgala			the environment the robot is from your screen. And is operated by giving your
	188W1A1203	Achanta Satya	II-A		commands using the transmitter and receiver embedded in it receives your commands.
		Deepika			The arduino processes your commands and finally the robot works accordingly.
13	178W1A1221	K.Saketh	III-A	Smart	Now-a-days both the parents in the house are working and because of this they leave
	178W1A1237	N.Dhruthi	III-A	Doorbell	their old parents or their children alone at home and if a single lady is living in a house, if
	178W1A1238	N.Raja	III-A		someone comes and rings the doorbell they might feel insecure to open the door and
		Rajeswari			the solution for this problem is "smart doorbell" which sends a picture to two persons of
					the family one through telegram and other through mail whether they are in or out of
					the house .
14	178W1A1288	K.Rachana	III-B	Fire Fighter	To rescue people and to put out the fire we are forced to use human resources which are
	178W1A1282	G.Aparna	III-B	Robot	not safe. With the advancement of technology especially in Robotics it is very much
					possible to replace humans with robots for fighting the fire .This would improve the
					efficiency of fire fighters and would also prevent them from risking human lives.
15	178W1A12B1	Sameera	III-B	Home	Home automation - controlling the fans, lights and other electrical appliances in a house
		Tasneem		Controlling	using Internet of things is widely preferred in recent days. In this project, we proposed
	178W1A12A1	Dharani.M	III-B	System Using	Google Assistant using by which the fans, lights and other electrical appliances can be
				Chabot	controlled over the Internet. The messages sent using the chatbot is processed using
					Natural Language processing techniques. Secondly, any device connected to the local
					area network of the house can control the devices and other appliances in the house.
					Thirdly, the web application used to enable home automation also has a security feature
					that only enables certain users to access the application. And finally, it also has a
					functionality of sending an email alert when intruder is detected using motion sensors.
17	178W1A12B9	Y.Alekya	III-B	Smart In	The main aim of the project is to develop a system which can automatically control break

	178W1A1297	K.Jhasni	III-B	Vehicle	system of vehicle and accident avoidance using sensors. Whenever any obstacle is
	178W1A12A5	M.Preethi	III-B	Transport	detected in running vehicle depends on distance automatically gives the driver an alert.
				System For	The IR sensors continuously sends signals and monitors any car or other obstacles are in
				road Users	front of car. Many accidents at High-ways are taking place due to the close running of
				Safety	vehicles, all of sudden, if the in front vehicle driver reduces the speed or applied breaks,
				5	then it is quite difficult to the following vehicle driver to control his vehicle, resulting in
					accident.
18	188W1A1288	M.Darahasa	II-B	Automated	Computerized systems being an integral part of the current era, an automated parking
	188W1A1289	Md.Nayeema	II-B	Parking	system is one of its most commonly used applications. This automated parking system
				System In	is designed to give access exclusively to vehicles. It takes the image of the vehicle and
				Matlab	identifies its license number. It then checks with the database to determine its access.
					This report is a detailed description of the image processing techniques used for
					Automatic Number Plate Recognition. It deals with computer vision and the various
					techniques used in image processing. This system requires the vehicle to be physically
					present, so that security is not hampered with and access is denied to any vehicle that is
					not registered.
20	178W1A1251	P.Sravya Reddy	III-A	Smart Mirror	When we are standing in front of the mirror just switch on the power. The setup starts
	178W1A1223	K.Lasya Sri	III-A		automatically and it displays weather report, date and time, our daily schedule and
		-			moreover it displays daily news on the mirror. Apart from that it also displays the
					comment lines to remind us lunch and dinner at respective time. Also we can customize
					the news by channels which we want to take a look. We can set our daily events on our
					mobile phone and it gets updated and displays the new events.
21	188W1A1286	K.Sai Lakshmi	II-B	Smart Alarm	The alarm wakes us up by producing sound but what about deaf people how they will
	188W1A1287	K.Sri Lakshmi	II-B	For Deaf	listen to the alarm ring. Some people have dealt with this problem and have come up till
					vibrations(vibrating alarm clock), but vibrations have some harmful effects on body even
					if the degree of harm is less, vibrations are a bit harsh way of waking them up.
22	188W1A12A9	T.Jahnavi	II-B	Online	The system uses sensor technology along with microcontroller and other electronics in
		Lakshmi		Vehicle	order to behave like smart switching system which senses soil moisture level and
	188W1A12B0	V.Anusha	II-B	Parking Slot	irrigates the plant if necessary. Purpose of this work is to show how someone can easily
				Booking	make own and cheap automatic plant watering system in just few hours by connecting
				-	certain electronic components and other materials required. In our experiment.

Some of the Photographs

SIGN LANGUAGE INTERPRETER



FIRE FIGHTER ROBO



FARM'S UMBRELLA



SMART DOOR BELL



SMART MIRROR



SMART DUSTBIN

